

10-423/10-623 Generative Al

Machine Learning Department School of Computer Science Carnegie Mellon University

Video Generation and Understanding

Matt Gormley & Henry Chai Lecture 25 Dec. 4, 2024

Reminders

• HW623

- Only for students registered in 10-623
- Due: Mon, Dec 2 at 11:59pm
- Submit form: https://forms.gle/azrmUR9KrFexnASi7
- Project Poster
 - Upload Due: Tue, Dec 10 at 11:59pm
 - Presentations: Fri, Dec 13 at 1pm-4pm
- Project Final Report
 - Due: Fri, Dec 13 at 11:59pm
- Project Code Upload
 - Due: Fri, Dec 13 at 11:59pm

Video Generation and Understanding

- Outline
 - video generation (video diffusion models)
 - 3D Unet (2016)
 - VViT & Spatio-Temporal Attention (2021)
 - Video Diffusion Model (2022)
 - Video Latent Diffusion Model (2023)
 - Diffusion Transformer (2023)
 - Sora (2024)
 - video understanding (visual language models)
 - Llava (understand text+image)
 - Video-Llava (understand text+image+video)
 - QwenVL (understand text+image+video)
 - Large World Model (generate/understand text+image+video)

VIDEO DIFFUSION MODELS

Datasets for Video Models

Dataset	Year	Text	Domain	#Clips	Resolution
MSR-VTT [271]	2016	Manual	Open	10 K	240P
DideMo [3]	2017	Manual	Flickr	27 K	
LSMDC [192]	2017	Manual	Movie	118 K	1080P
ActivityNet [119]	2017	Manual	Action	100 K	—
YouCook2 [307]	2018	Manual	Cooking	14 K	—
How2 [202]	2018	Manual	Instruct	80 K	_
VATEX [245]	2019	Manual	Action	41 K	240P
HowTo100M [162]	2019	ASR	Instruct	136 M	240P
WTS70M [217]	2020	Metadata	Action	70 M	—
YT-Temporal [290]	2021	ASR	Open	180 M	-
WebVid10M [5]	2021	Alt-text	Open	10.7 M	360P
Echo-Dynamic [191]	2021	Manual	Echocardiogram	10 K	1
Tiktok [241]	2021	Mannual	Action	0.3 K	_
HD-VILA [273]	2022	ASR	Open	103 M	720P
VideoCC3M [167]	2022	Transfer	Open	10.3 M	—
HD-VG-130M [244]	2023	Generated	Open	130 M	720P
InternVid [250]	2023	Generated	Open	234 M	720P
CelebV-Text [286]	2023	Generated	Face	70 K	480P
Panda-70M [28]	2024	Generated	Open	70.8 M	720P

Datasets for Video Models

- The largest datasets of videos with captions use a model to generate the captions
- The quality and style of the captions can vary wildly depending on which model is used

HDVILA-100M



"Yeah, now everybody thought that we couldn't replace cat; yeah, because you're such animal lovers."



"It's good that we have aquariums they bring this wonderful experience into our homes for special moments"



"We're gonna cook this all together stirring it constantly for just a minute until it smells nice and fragrant."



"He thought he was gonna get shows terrible communication on the teams part."

Panda-70M (Ours)



"It is a close-up shot of a brown and white english bulldog with wrinkles on its face, sitting on a person's lap."



"It is a red and purple betta fish swimming in a tank with gravel and plants."



"A person is adding chicken broth to a pot of quinoa on a stove."



"A basketball player is dribbling the ball and shooting it into the hoop."

Figure 1. **Comparison of Panda-70M to the existing large-scale video-language datasets.** We introduce Panda-70M, a large-scale video dataset with captions that are annotated by multiple cross-modality vision-language models. Compared to text annotations in existing dataset [80], captions in Panda-70M more precisely describe the main object and action in videos (highlighted in green). Besides, videos in Panda-70M are semantically coherent, high-resolution, and free from watermarks. More samples can be found in Appendix E.

Panda-70M Examples: https://snap-research.github.io/Panda-70M/

Figure from http://arxiv.org/abs/2402.19479

- Architecture = <u>3D</u> UNet + spatial-temporal attention
- Relative positional embeddings across time axis

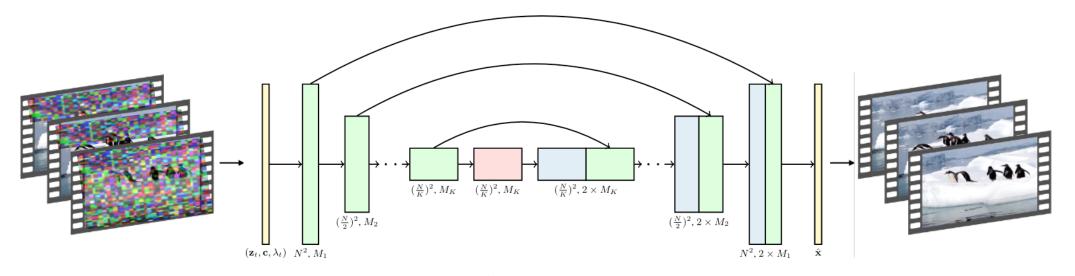
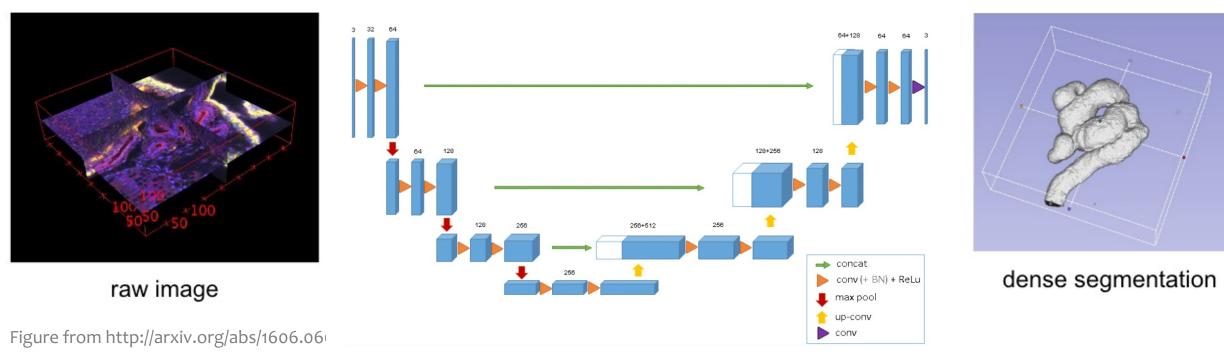


Figure 1: The 3D U-Net architecture for $\hat{\mathbf{x}}_{\theta}$ in the diffusion model. Each block represents a 4D tensor with axes labeled as frames × height × width × channels, processed in a space-time factorized manner as described in Section 3. The input is a noisy video \mathbf{z}_t , conditioning \mathbf{c} , and the log SNR λ_t . The downsampling/upsampling blocks adjust the spatial input resolution height × width by a factor of 2 through each of the K blocks. The channel counts are specified using channel multipliers M_1 , M_2 , ..., M_K , and the upsampling pass has concatenation skip connections to the downsampling pass.

3D UNet

- Suppose you want to do image segmentation on 3D images (e.g. high-resolution, 3D imaging of a *Xenopus* kidney)
- The 3D UNet model is almost identical to the standard UNet except that it replaces 2D convolution (height, width, channel) with 3D convolution (height, width, **depth**, channel)

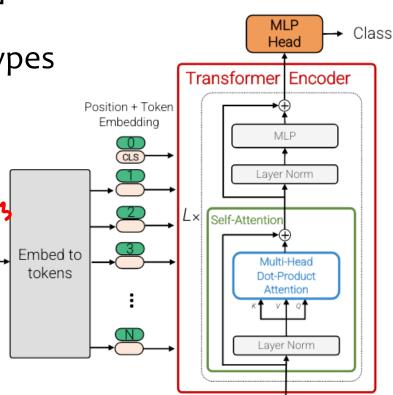


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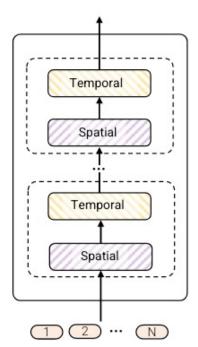
Video Vision Transformer (VViT)

- The Video ViT takes a series of image frames from a video as input
- A standard ViT model for images would treat each frame as independent (i.e. only has spatial attention across the [w,h] axes)
- The Video ViT instead includes two types of attention: spatial attention and temporal attention

n +04







Factorized Spatial-Temporal Attention

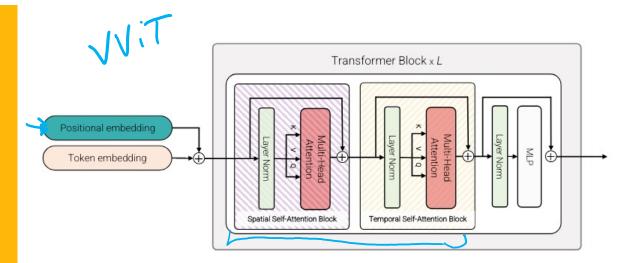
VViT alternate between the two types:

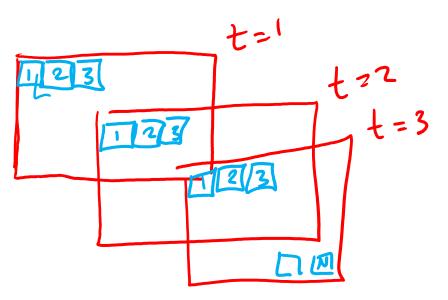
Spatial attention:

- 1. reshape: $b t h w c \rightarrow (b t) (h w) c$
- 2. multi-headed attention
- 3. reshape: (b t) (h w) c -> b t h w c

Temporal attention:

- 1. reshape: b t h w c -> (b h w) t c
- 2. multi-headed attention
- 3. reshape: (b h w) t c -> b t c h w





- Architecture = 3D UNet + spatial-temporal attention
- Relative positional embeddings across time axis

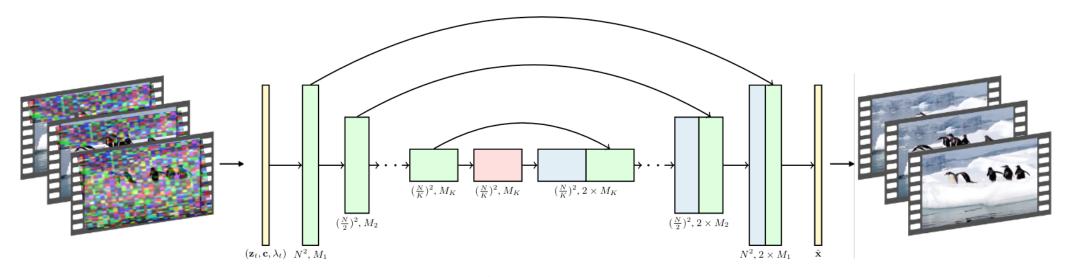


Figure 1: The 3D U-Net architecture for $\hat{\mathbf{x}}_{\theta}$ in the diffusion model. Each block represents a 4D tensor with axes labeled as frames × height × width × channels, processed in a space-time factorized manner as described in Section 3. The input is a noisy video \mathbf{z}_t , conditioning c, and the log SNR λ_t . The downsampling/upsampling blocks adjust the spatial input resolution height × width by a factor of 2 through each of the K blocks. The channel counts are specified using channel multipliers M_1 , M_2 , ..., M_K , and the upsampling pass has concatenation skip connections to the downsampling pass.

Video Diffusion Model Figure from

Figure from http://arxiv.org/abs/2304.08818

- The model can be **jointly** trained on **images and video**
- When trained on images, the temporal attention is **masked** so that all the attention mass is placed on the current batch element
- Such training improves performance on video generation

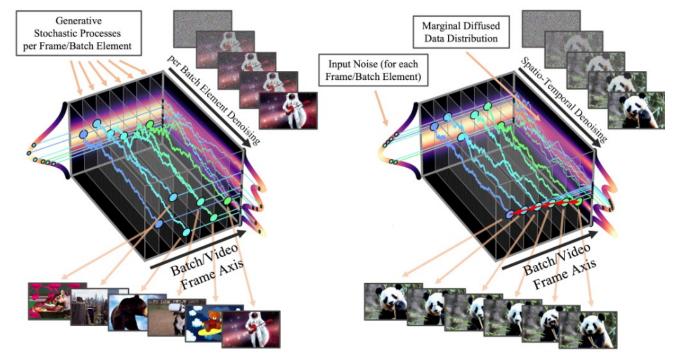


Image frames	FVD↓	FID-avg↓	IS-avg↑	FID-first↓	IS-first↑
0	202.28/205.42	37.52/37.40	7.91/7.58	41.14/40.87	9.23/8.74
4	68.11/70.74	18.62/18.42	9.02/8.53	22.54/22.19	10.58/9.91
8	57.84/60.72	15.57/15.44	9.32/8.82	19.25/18.98	10.81/10.12

• Classifier-free Guidance

$$\tilde{\boldsymbol{\epsilon}}_{\theta}(\mathbf{z}_t, \mathbf{c}) = (1+w)\boldsymbol{\epsilon}_{\theta}(\mathbf{z}_t, \mathbf{c}) - w\boldsymbol{\epsilon}_{\theta}(\mathbf{z}_t),$$

- Suppose we want to sample from a conditional distribution: $p_{ heta}(\mathbf{x}^{b}|\mathbf{x}^{a})$
 - x^{a} could be the first 16 frames, and now we want to generate the next 16 frames x^{b}
 - or \mathbf{x}^a could be a low frame rate video and \mathbf{x}^b are the frames in between to increase framerate
- Reconstruction Guided Sampling
 - key idea: guide the sample "based on the model's reconstruction of the conditioning data"

$$\tilde{\mathbf{x}}_{\theta}^{b}(\mathbf{z}_{t}) = \hat{\mathbf{x}}_{\theta}^{b}(\mathbf{z}_{t}) - \frac{w_{r}\alpha_{t}}{2} \nabla_{\mathbf{z}_{t}^{b}} \|\mathbf{x}^{a} - \hat{\mathbf{x}}_{\theta}^{a}(\mathbf{z}_{t})\|_{2}^{2}$$

Reconstruction Guided Sampling

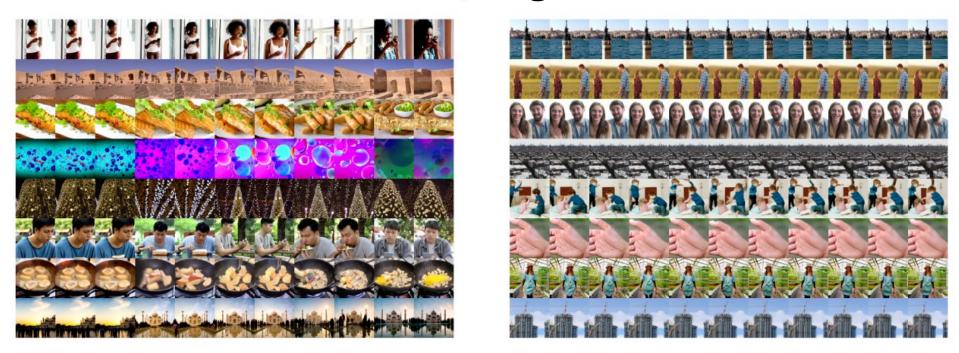


Figure 4: Comparing the replacement method (left) vs the reconstruction guidance method (right) for conditioning for block-autoregressive generation of 64 frames from a 16 frame model. Video frames are displayed over time from left to right; each row is an independent sample. The replacement method suffers from a lack of temporal coherence, unlike the reconstruction guidance method.

Results

• In video prediction, we are given the beginning of a video and we see how well the model can complete it

Table 2:	Video prediction	on BAIR Robot Pushing.
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Method	FVD↓
DVD-GAN [14]	109.8
VideoGPT [62]	103.3
TrIVD-GAN-FP [33]	103.3
Transframer [35]	100
CCVS [31]	99
VideoTransformer [59]	94
FitVid [4]	93.6
NUWA [61]	86.9
Video Diffusion (ours)	
ancestral sampler, 512 steps	68.19
Langevin sampler, 256 steps	66.92

Table 3: Video prediction on Kinetics-600.				
Method	FVD↓	IS↑		
Video Transformer [59]	170 ± 5			
DVD-GAN-FP [14]	69.1 ± 0.78			
Video VQ-VAE [57]	64.3 ± 2.04			
CCVS [31]	55 ± 1			
TrIVD-GAN-FP [33]	25.74 ± 0.66	12.54		
Transframer [35]	25.4			
Video Diffusion (ours)				
ancestral, 256 steps	18.6	15.39		
Langevin, 128 steps	$\textbf{16.2} \pm \textbf{0.34}$	15.64		

Results

• In video prediction, we are given the beginning of a video and we see how well the model can complete it

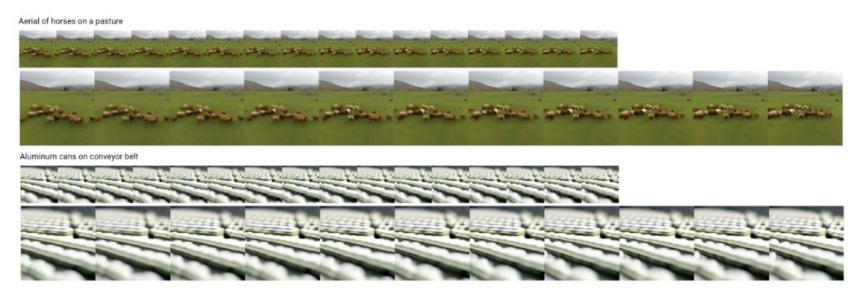


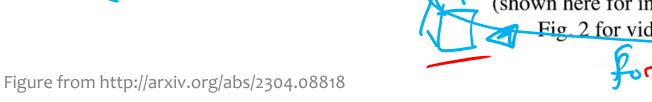
Figure 2: Text-conditioned video samples from a cascade of two models. First samples are generated from a 16x64x64 frameskip 4 model. Then those samples are treated as ground truth for simultaneous super-resolution and autoregressive extension to 64x128x128 using a 9x128x128 frameskip 1 model. Both models are conditioned on the text prompt. In this figure, the text prompt, low resolution frames, and high resolution frames are visualized in sequence. See Fig. 5 for more samples.

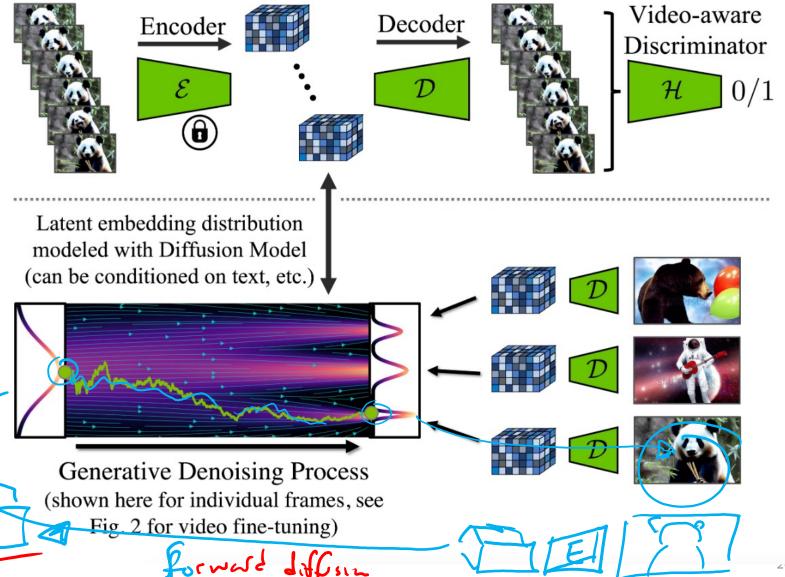
Figure from https://proceedings.neurips.cc/paper_files/paper/2022/hash/39235c56aef13fb05a6adc95eb9d8d66-Abstract-Conference.html

• Demo: <u>https://video-diffusion.github.io/</u>

Video Latent Diffusion Model (VLDM)

- The VLDM model combines two pieces:
 - Encoder/Decoder trained to reconstruct convert videos down to a latent representatior and then reconstruct them
 - A video diffusion model trained to work in the latent space





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Figure from http://arxiv.org/abs/2304.08818

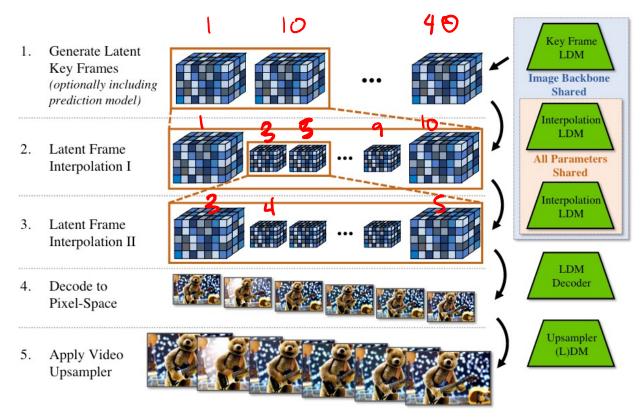


Figure 5. Video LDM Stack. We first generate sparse key frames. Then we temporally interpolate in two steps with the same interpolation model to achieve high frame rates. These operations are all based on latent diffusion models (LDMs) that share the same image backbone. Finally, the latent video is decoded to pixel space and optionally a video upsampler diffusion model is applied.

Video Latent Diffusion Model (VLDM)

• Demo: <u>https://research.nvidia.com/labs/toronto-ai/VideoLDM/</u>

Diffusion Transformer

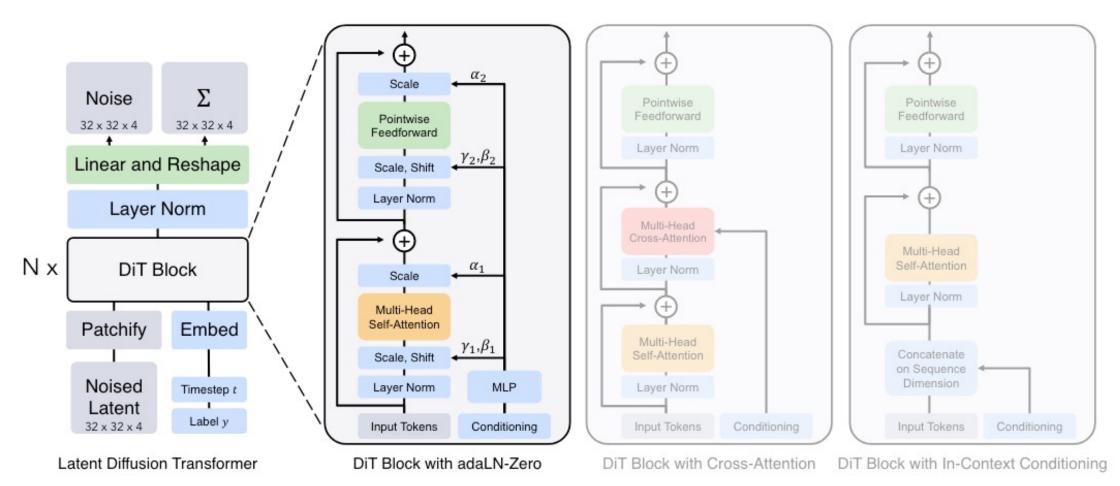


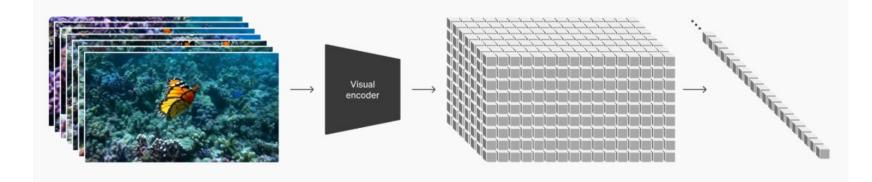
Figure 3. The Diffusion Transformer (DiT) architecture. Left: We train conditional latent DiT models. The input latent is decomposed into patches and processed by several DiT blocks. *Right:* Details of our DiT blocks. We experiment with variants of standard transformer blocks that incorporate conditioning via adaptive layer norm, cross-attention and extra input tokens. Adaptive layer norm works best.

Diffusion Transformer



Figure 1. Diffusion models with transformer backbones achieve state-of-the-art image quality. We show selected samples from two of our class-conditional DiT-XL/2 models trained on ImageNet at 512×512 and 256×256 resolution, respectively.

Sora

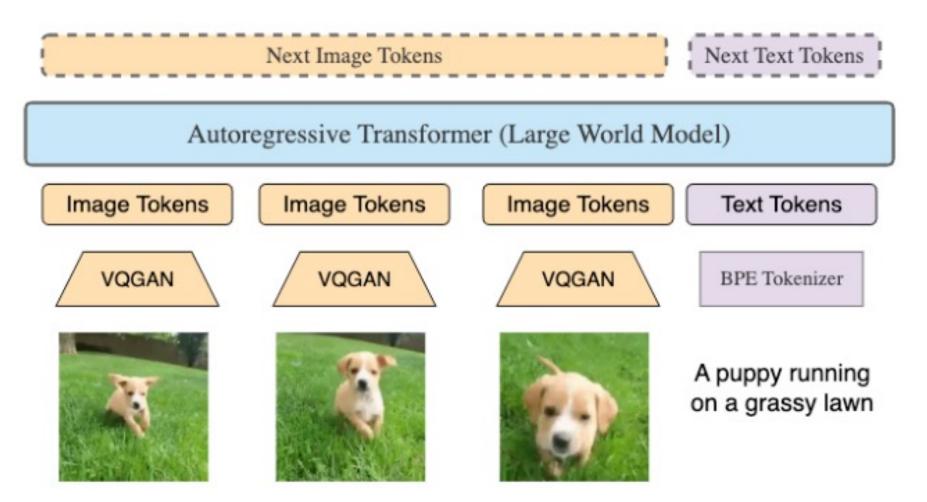


Sora uses a Diffusion Transformer backbone trained on images and videos



VIDEO AND VLMS

Large World Model



Large World Model

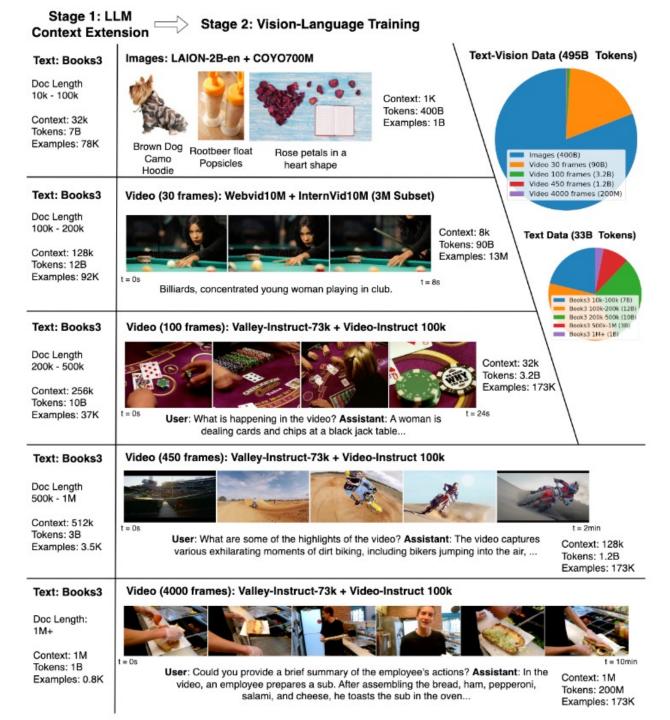


Figure from http://arxiv.org/abs/2402.08268

Large World Model



An elephant

under the sea

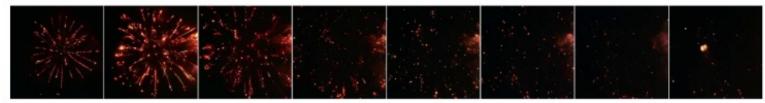
A black dog



A cube made of denim



A glass of wine A yellow and black bus cruising through a rainforest



Fireworks exploding in the sky



Waves crashing against the shore

Figure 8 LWM can generate images and videos given text input. Examples of image and video generations. More examples are shown in Appendix E and Appendix D.