
Kernels, SVM

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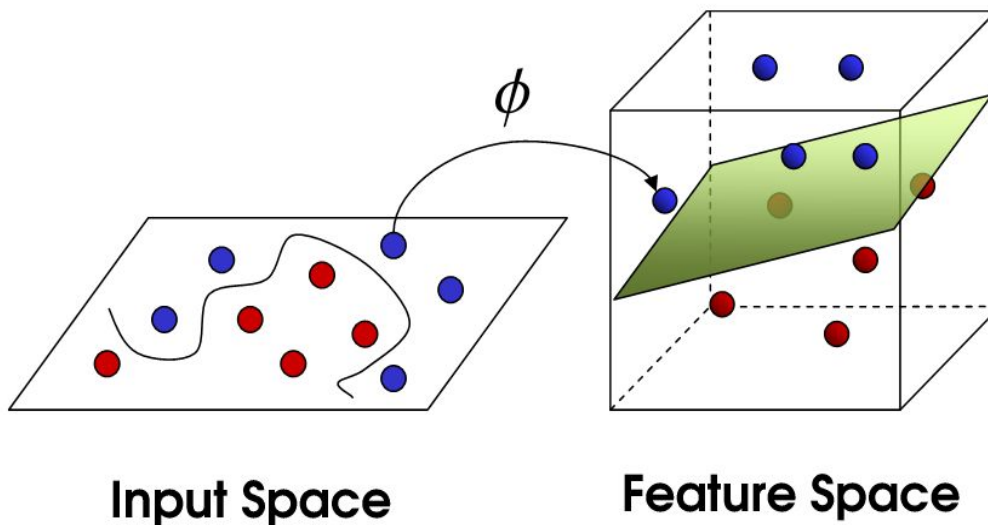
Kernel Overview

- What if data is not linearly separable?
 - Switch to a more complicated class of functions
 - Use a Kernel!

- Kernels are a “legal definition” of a dot product: there exists Φ such that $K(x,y)=\Phi(x) \cdot \Phi(y)$

Key Ideas

- By using the kernel we move into a higher dimension space
- Imperative to think of the Kernel Function **IMPLICITLY**



Why think about Φ implicitly?

- Feature space can grow rapidly
- Avoid computing actual values of coordinates in the feature space
 - “KERNEL TRICK”
 - Just take inner products
- Computationally cheaper than explicitly calculating values

Common Kernels and Commonly Kernelizable Algos

Linear: $K(x, z) = x \cdot z$

Polynomial: $K(x, z) = (x \cdot z)^d$ or $K(x, z) = (1 + x \cdot z)^d$

Gaussian: $K(x, z) = \exp \left[-\frac{\|x-z\|^2}{2 \sigma^2} \right]$

Laplace Kernel: $K(x, z) = \exp \left[-\frac{\|x-z\|}{2 \sigma^2} \right]$

- Perceptron
- SVM
- Linear Regression
- Ridge Regression
- K-Means

Margins

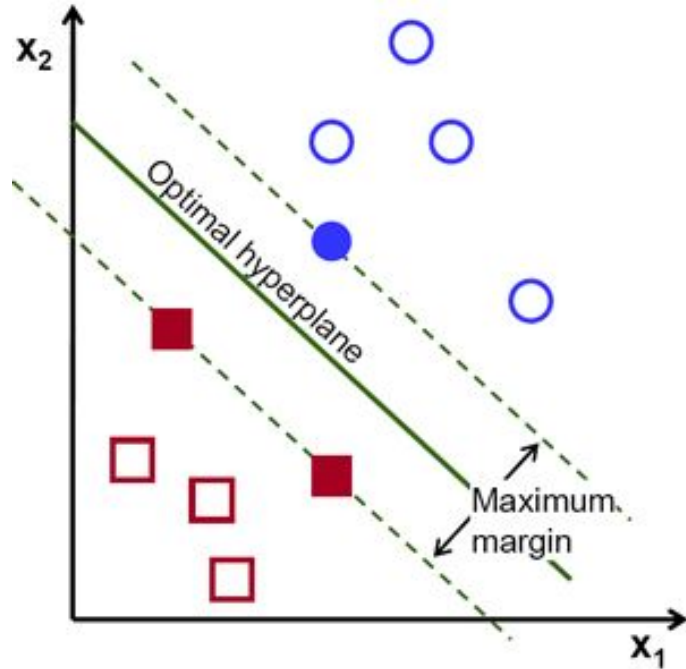
- Having a large margin will prevent overfitting
- Why not directly search for a large margin classifier?

SVM

- Optimize for the maximum margin separator
- Most stable under noise

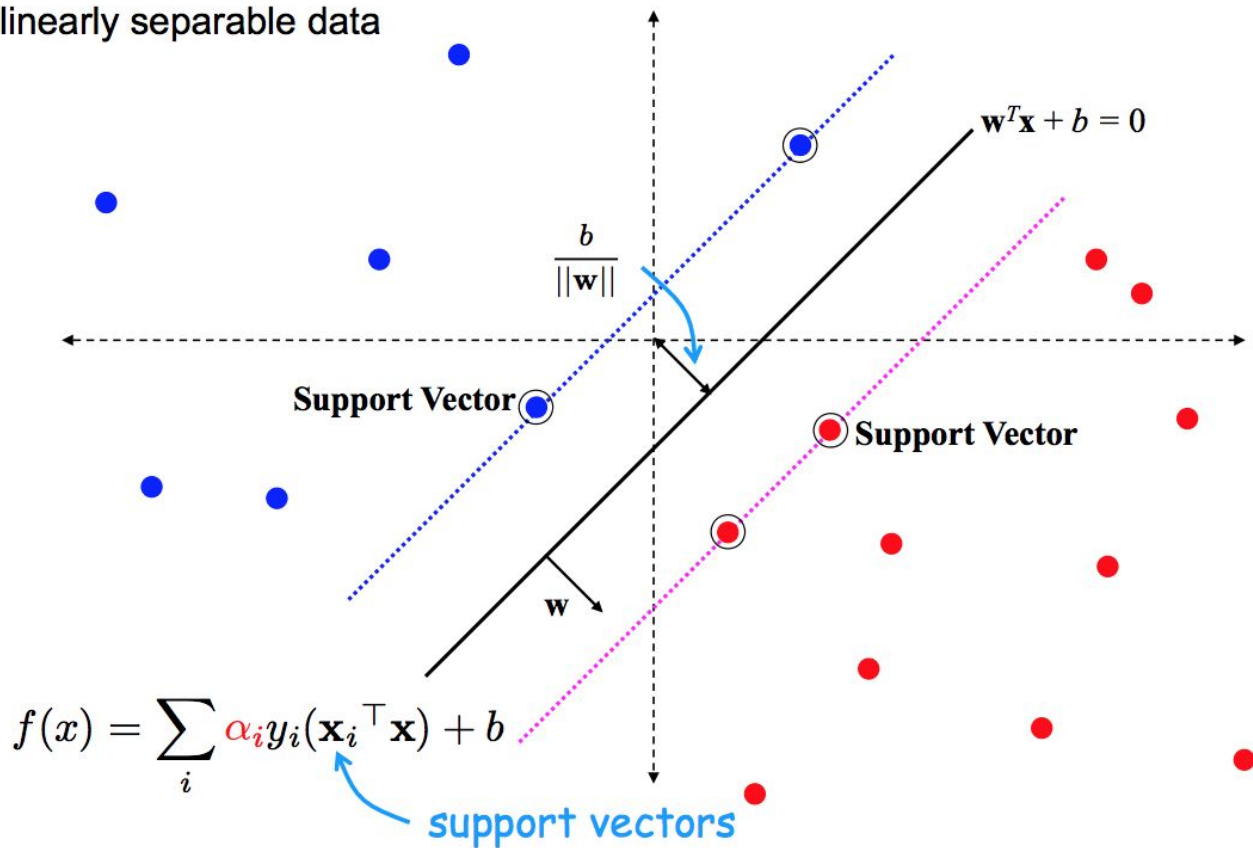
Idea

- Support Vector Machines attempt to directly learn the linear separator with the largest margin

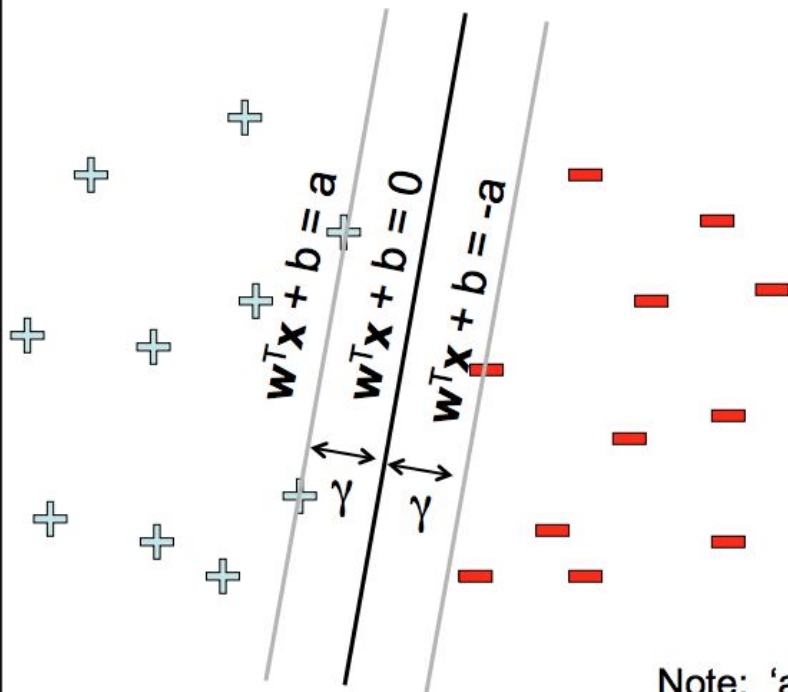


Support Vector Machine

linearly separable data



Maximizing the margin



Margin = Distance of
closest examples
from the decision line/
hyperplane

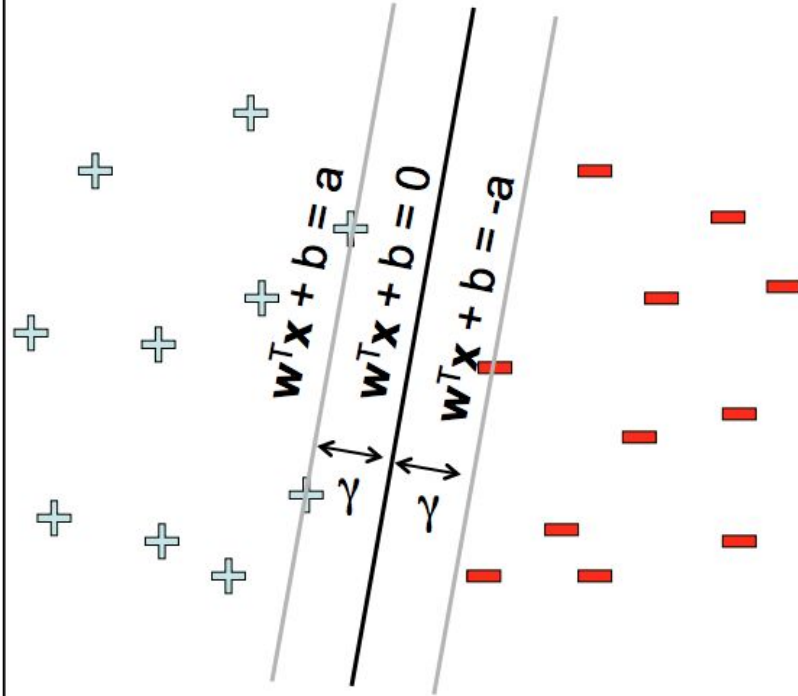
$$\text{margin} = \gamma = a/\|w\|$$

$$\max_{w,b} \gamma = a/\|w\|$$

$$\text{s.t. } (w^T x_j + b) y_j \geq a \quad \forall j$$

Note: 'a' is arbitrary (can normalize
equations by a)

Support Vector Machine



$$\min_{w,b} w^T w$$

$$\text{s.t. } (w^T x_j + b) y_j \geq 1 \quad \forall j$$

Solve efficiently by quadratic programming (QP)

- Well-studied solution algorithms

Linear hyperplane defined by “support vectors”

Any Questions?

Slides taken from Tom Mitchell, Nina Balcan, Oxford University