

Lecture 24: Spectral Graph Theory I

1

[Questions motivating us now...]: Given undirected graph G .

- how to "cluster" vertices into 2+ groups?
- how to "visualize" in 2 or 3 dims?
- how long does random walk take to get "close" to stationary dist?

Henceforth for simplicity: G is d-regular.

$$K = \begin{bmatrix} \text{Adj. Matrix} \\ \vdots d_1 \vdots d_2 \cdots \vdots d_n \end{bmatrix} = \frac{1}{d} A$$

symmetric, $K = K^T$

{Everything has appropriate analogues for non-regular graphs, but math & formulas get a little annoying; let's keep things simple!}

{Remember I told you linear algebra is **ICOR** easier with symmetric matrices? This is one example.}

Stationary distribution: $\pi[u]$ proportional to $\deg[u] \dots \therefore \pi = \begin{bmatrix} \frac{1}{n} \\ \vdots \\ \frac{1}{n} \end{bmatrix}$ = uniform dist. ☺

$K\pi = \pi \Rightarrow \pi$ is eigenvect of K , eigenvalue 1.

{we'll talk about eigenvects more soon.}

Say for each vertex $v \in V$ we have a real # data value $f(v)$.

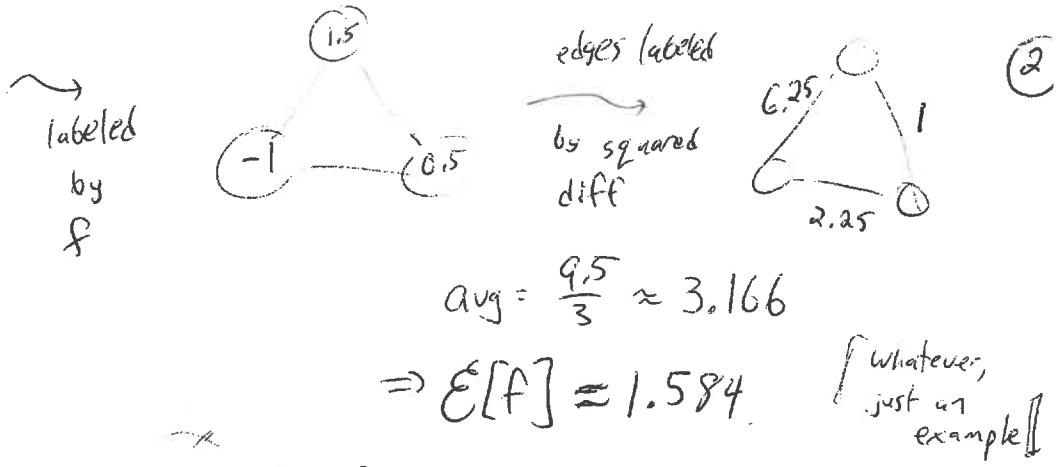
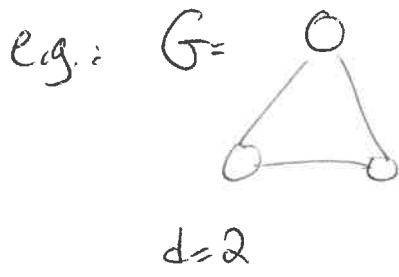
{Could be anything - temperature, color, id, height, x-coord. in a plot...} $f: V \rightarrow \mathbb{R}$

define: $E[f] = \frac{1}{2} \overbrace{\mathbb{E}}^{\text{average}}_{(u,v) \text{ edge}} [(f(u) - f(v))^2]$

"energy"
"quadratic
form",
what?

"average variance
on edges"

{don't worry about too much;
just convenient to have
this factor!}



* e.g. Let $S \subseteq V$. Let $f(v) = \begin{cases} 1 & \text{if } v \in S \\ 0 & \text{if } v \notin S \end{cases}$ What's $E[f]$?

$$E[f] = \frac{1}{2} \sum_{\substack{(u,v) \\ \text{edge}}} \left[(f(u) - f(v))^2 \right]$$

~~C if $u, v \in S$ or $u, v \notin S$~~

$(\pm 1)^2 = 1$ if u, v on "opp. sides": (u, v) crosses "cut"

$$= \frac{1}{2} \Pr_{\substack{(u,v) \\ \text{edge}}} \left[u \in S, v \notin S \text{ or } u \notin S, v \in S \right]$$

(S, \bar{S})

$$= \Pr_{\substack{(u,v) \\ \text{edge} \\ (\text{directed!})}} \left[u \in S, v \notin S \right]$$

" $u \rightarrow v$ is stepping out of S "

= "fractional size of boundary of S "



[Has something to do with how long it takes random walk to "escape out of S ".]

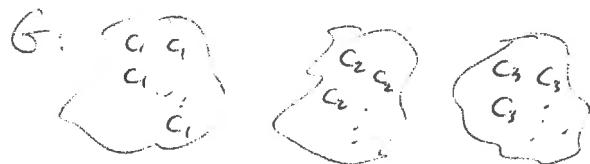
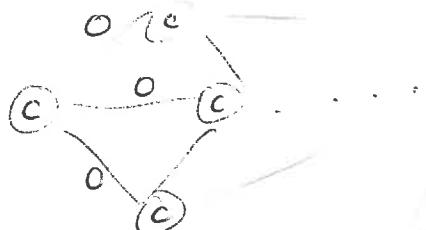
Fact: $E[f] \geq 0$ always. [Why? Well, it's avg. of squares, ≥ 0 .]

Q: For what f is $E[f] = 0$?

A: $f(v) = 0 \forall v$, $f(v) = 1 \forall v$, $f(v) = c \forall v$ [Anything else?]

That's it if G is connected.

Say now G might be disconnected.



We'll think of $f: V \rightarrow \mathbb{R}$ as a vector: $\begin{bmatrix} f(v_1) \\ f(v_2) \\ \vdots \\ f(v_n) \end{bmatrix} \in \mathbb{R}^n$.

Say G has 3 connected comps, S_1, S_2, S_3 .

Then $\exists 3$ linearly independent f 's with $E[f] = 0$:

$$S_1 \left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \\ 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, S_2 \left\{ \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, S_3 \left\{ \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix} \right. \right. \right.$$

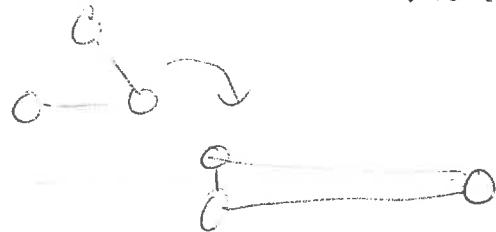
[and every f with $E[f] = 0$ is a lin. combo of them, coeffs c_1, c_2, c_3 .]

Connection between linear algebra & graph theory!]

What's largest $E[f]$ can be? [Well.. ∞ . We need to fix some "scaling".]

~ Multiplying f by k multiplies $E[f]$ by $\underline{k^2}$. [So the natural way to scale is also quadratic.]

Say f "normalized" if $\mathop{\mathbb{E}}_{v \text{ vertex}}^{(\text{avg})} [f(v)^2] = 1$. [Can always mult by a const. to achieve this.]



[Trying to map vertices $v \in V$ into real line - avg-squared dist to 0 = 1 — so that edges "stretched" as much as possible.]

(What graph might allow for a very large E ?]

Say G is bipartite: vertices U, V , all edges between them. Let $f(w) = \begin{cases} +1 & \text{if } w \in U \\ -1 & \text{if } w \in V \end{cases}$. Normalized? ✓

$$\mathbb{E}[f(w)^2] = \mathbb{E}[(\pm 1)^2] = 1.$$

$$E[f] = \frac{1}{2} \mathbb{E}_{\substack{(u,v) \\ \text{edge}}} \left[\frac{(f(u) - f(v))^2}{(\pm 2)^2} \right] = 2.$$

Prop: For normalized f , $E[f] \leq 2$ always; equality possible iff G is bipartite.

Proof: $E[f] = \frac{1}{2} \left(E_{\substack{(u,v) \\ \text{edge}}} [f(u)^2] - 2E_{\substack{(u,v) \\ \text{edge}}} [f(u)f(v)] + E_{\substack{(u,v) \\ \text{edge}}} [f(v)^2] \right)$

$\sum u$ is a unit.
rand. vertex
[regularity]

normalized

$$= \frac{1}{2} (1) - \frac{1}{2} 2E_{\substack{(u,v) \\ \text{edge}}} [f(u)f(v)] + \frac{1}{2} (1) = 1 - E[f(u)f(v)] \leq 2$$

provided - . . .

Claim: $\left| \mathbb{E}_{\substack{(u,v) \\ \text{edge}}} [f(u)f(v)] \right| \leq 1$. Proof: ~~(Cauchy-Schwarz)~~ "Cauchy-Schwarz": $\left| \mathbb{E}[XY] \right| \leq \sqrt{\mathbb{E}[X^2]} \sqrt{\mathbb{E}[Y^2]}$

Spectral Graph Theory: • G has $\approx k$ "almost disconnected" clusters

$\Leftrightarrow E[f_1], \dots, E[f_k] \approx 0$ for
 \leftarrow lin. independent f_1, \dots, f_k

- G is almost bipartite $\Leftrightarrow E[f] \approx 2$ for some f
 $(= \text{huge max cut})$

[Where do eigenvalues come in?] [Hast here...] [E.g., if \mathbf{f} not big, how to find \mathbf{f} maximizing $E[\mathbf{f}]$?]

What is $h(u) = \sum_i f(v_i)$?

$$u \rightarrow \begin{bmatrix} K \\ -y_1 - y_2 - y_3 \\ \vdots \\ 1 \end{bmatrix} \begin{bmatrix} f(v_1) & f(v_2) & \dots & f(v_d) \end{bmatrix} = \begin{bmatrix} h \end{bmatrix}$$

at any $(u, v_1), (u, v_2), \dots, (u, v_d)$

(Applying k to f: replace each data value with average over neighbors.)

$$\det: \text{Inner product: } \langle f, g \rangle = \frac{1}{n} (f \circ g) = \frac{1}{n} (f(v_1)g(v_1) + \dots + f(v_n)g(v_n)) \quad (S)$$

$$= \mathbb{E}_{\text{vertex}} [f(v_i)g(v_i)]$$

["correlation between $f, g"]$

$$\langle f, f \rangle = \mathbb{E}[f(v_i)^2] = 1 \quad \text{iff } f$$

"sorta like "unit vec""

$Q:$ What is $\mathbb{E}[f]$?

$$A: \mathbb{E}[f(u) \cdot (Kf)(u)] = \mathbb{E}_u \left[f(u) \cdot \mathbb{E}_v [f(v)] \right] = \mathbb{E}_v [f(u)f(v)]$$

$$\begin{aligned} & \text{(normalized)} \\ & \mathbb{E}[f(u)f(v)] = \mathbb{E}_v [f(v)^2] + \mathbb{E}_v [f(v)]^2 \\ & = \frac{1}{2} \langle f, f \rangle - \frac{1}{2} \langle f, Kf \rangle + \frac{1}{2} \langle f, f \rangle \\ & = \langle f, f \rangle - \langle f, Kf \rangle \\ & = \langle f, f - Kf \rangle = \langle f, I^\top f - Kf \rangle \\ & = \langle f, (I - K)f \rangle \end{aligned}$$

"Pretty natural!"

$$Q: \text{What is } \mathbb{E}[f]?$$

$$A: = \frac{1}{2} \mathbb{E}_{\substack{(u,v) \\ \text{edge}}} [(f(u) - f(v))^2] = \frac{1}{2} \left(\mathbb{E}_u [f(u)^2] - 2 \mathbb{E}_u [f(u)f(v)] + \mathbb{E}_v [f(v)^2] \right)$$

$$= \frac{1}{2} \langle f, f \rangle - \frac{1}{2} \langle f, Kf \rangle + \frac{1}{2} \langle f, f \rangle$$

$$= \langle f, f \rangle - \langle f, Kf \rangle$$

ident mtx

$$= \langle f, f - Kf \rangle = \langle f, I^\top f - Kf \rangle$$

$$= \langle f, (I - K)f \rangle$$

$$\text{def: Laplacian matrix of } G: L := I - K = I - \frac{1}{2} A = \frac{1}{2}(I - A)$$

The reason to care about it is not that $I - K$ is inherently meaningful just that... $\mathbb{E}[f] = \langle f, Lf \rangle = \frac{1}{n} f^\top - \frac{1}{n} \int_L f$

Recall: A symmetric matrix like L stretches \mathbb{R}^n by stretch factors (eigenvalues) $\lambda_1, \dots, \lambda_n$ along axes (orthonormal eigenvectors) f_1, \dots, f_n .

~~say~~ f_i normalized. $Lf_i = \lambda_i \cdot f_i$

$$\Rightarrow \langle f_i, Lf_i \rangle = \langle f_i, \lambda_i f_i \rangle = \lambda_i \underbrace{\langle f_i, f_i \rangle}_{=1} = \lambda_i$$

$$\therefore \mathbb{E}[f_i] = \lambda_i \quad \therefore \text{all } \lambda_i \text{ are between 0 \& 2.}$$

⑥

if G has k connected components
then κ of the sets are Q
 \Leftrightarrow κ is the size of the
largest component

number

of