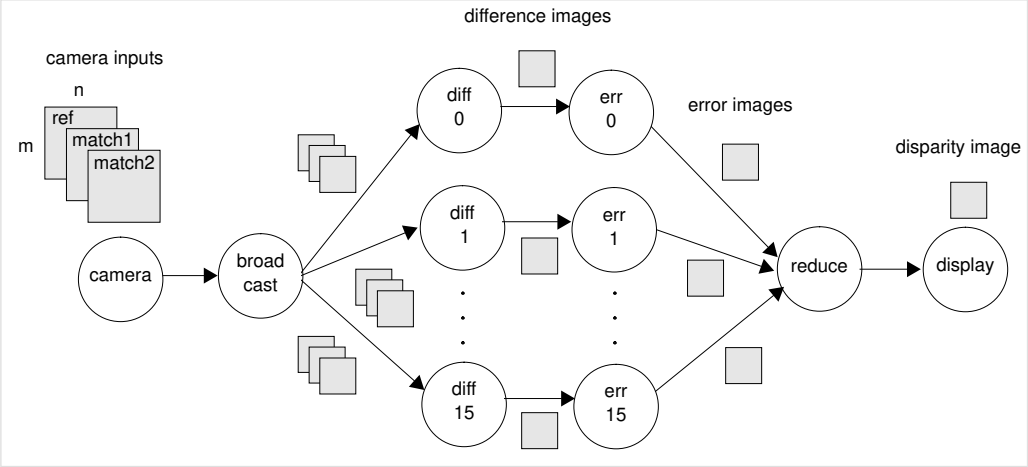
difference images
camera inputs
n
m
ref
match1
match2
camera
broad
cast
diff
0
diff
1
diff
15
err
0
err
1
err
15
error images
reduce
disparity image
display