# 15-399 Supplementary Notes: Substitution

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# Substitution

We will make frequent use of *substitution* of a term, M, for the free occurrences of a variable, u, in another term, N. This is written [M/u]N. The intuitive idea is clear, but there are pitfalls that must be avoided; some examples are given in the Pfenning notes. Here we give a precise definition of substitution to have as a reference.

## Free and Bound Variables

First we define the set FV(M) of *free variables* occurring in M.

$$\begin{array}{rcl} \mathrm{FV}(u) &=& \left\{ u \right\} \\ \mathrm{FV}(\langle \rangle) &=& \emptyset \\ \mathrm{FV}(\langle M_1, M_2 \rangle) &=& \mathrm{FV}(M_1) \cup \mathrm{FV}(M_2) \\ \mathrm{FV}(\mathbf{fst}(M)) &=& \mathrm{FV}(M) \\ \mathrm{FV}(\mathbf{snd}(M)) &=& \mathrm{FV}(M) \\ \mathrm{FV}(\mathbf{snd}(M)) &=& \mathrm{FV}(M) \\ \mathrm{FV}(\lambda u : P \cdot M) &=& \mathrm{FV}(M) \setminus \left\{ u \right\} \\ \mathrm{FV}(M_1 \cdot M_2) &=& \mathrm{FV}(M_1) \cup \mathrm{FV}(M_2) \\ \mathrm{FV}(\mathbf{abort}_P(M)) &=& \mathrm{FV}(M) \\ \mathrm{FV}(\mathbf{inl}(M)) &=& \mathrm{FV}(M) \\ \mathrm{FV}(\mathbf{inl}(M)) &=& \mathrm{FV}(M) \\ \mathrm{FV}(\mathbf{inr}(M)) &=& \mathrm{FV}(M) \\ \mathrm{FV}(\mathbf{ase} \ M \ \mathbf{of} \ \mathbf{inl}(u_1) \Rightarrow M_1 \mid \mathbf{inr}(u_2) \Rightarrow M_2) &= \\ \mathrm{FV}(M) \cup (\mathrm{FV}(M_1) \setminus \left\{ u_1 \right\}) \cup (\mathrm{FV}(M_2) \setminus \left\{ u_2 \right\}) \end{array}$$

If a variable u occurs in M, but  $u \notin FV(M)$ , then we say that u is *bound* in M. We say that M lies apart from N, written M # N, iff  $FV(M) \cap FV(N) = \emptyset$ . We most often use this notation in the form u # M, which therefore means  $u \notin FV(M)$ . In particular, u # v iff  $u \neq v$ .

#### **Renaming of Bound Variables**

Intuitively, the terms  $\lambda u: P.u$  and  $\lambda v: P.v$  are the "same", since they differ only in the name of the bound variable. Two terms that differ only in the names

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of their bound variables are said to be  $\alpha$ -equivalent, or  $\alpha$ -convertible.<sup>1</sup> It is remarkably tricky to give a precise definition of this relation.

We first define the notion of variable swapping. We write  $[u \leftrightarrow v]M$  to mean that all occurrences of u in M are to be replaced by v, and all occurrences of v in M are to be replaced by u. We emphasize "all", because the replacement applies even to binders such as  $\lambda$ . For example,  $[u \leftrightarrow v]\lambda v: P.u = \lambda u: P.v$ .

The relation  $M =_{\alpha} N$  is inductively defined by the following rules:<sup>2</sup>

$$\begin{split} \overline{u} &=_{\alpha} \overline{u} \quad \overline{\langle \rangle} =_{\alpha} \langle \rangle \quad \frac{M =_{\alpha} M' \quad N =_{\alpha} N'}{\langle M, N \rangle =_{\alpha} \langle M', N' \rangle} \\ \\ \frac{M =_{\alpha} M'}{\mathbf{fst}(M) =_{\alpha} \mathbf{fst}(M')} \quad \frac{M =_{\alpha} M'}{\mathbf{snd}(M) =_{\alpha} \mathbf{snd}(M')} \\ \\ \frac{M =_{\alpha} M'}{\lambda u : P \cdot M =_{\alpha} \lambda u : P \cdot M'} \quad \frac{u \ \# \ v \ v \ \# \ M \quad [u \leftrightarrow v] M =_{\alpha} M}{\lambda u : P \cdot M =_{\alpha} \lambda v : P \cdot M'} \end{split}$$

The last two lines are the most interesting. When comparing two  $\lambda$ 's that bind the same variable, we simply compare their bodies. If, however, they have different bound variables, then we replace u by v (and v by u) in the first to reconcile the difference, and continue comparing. Since v # M the replacement of v by u in M does not change any *free* variable, but ensures that no confusion can occur when replacing u by v in M due to *bound* occurrences of v in M.

 $<sup>^1{\</sup>rm The}$  origin of the phrase is essentially a historical accident, but this terminology is too deeply entrenched to be changed now.

 $<sup>^{2}</sup>$ We omit the rules for case analysis and abort for the sake of brevity.

#### Substitution

Substitution is inductively defined by the following clauses:

$$\begin{bmatrix} M/u \end{bmatrix} u = M \\ [M/u]v = v \qquad (u \neq v) \\ \begin{bmatrix} M/u \end{bmatrix} \langle \rangle = \langle \rangle \\ \begin{bmatrix} M/u \end{bmatrix} \langle N_1, N_2 \rangle = \langle [M/u] N_1, [M/u] N_2 \rangle \\ \begin{bmatrix} M/u \end{bmatrix} \mathbf{fst}(N) = \mathbf{fst}([M/u]N) \\ \begin{bmatrix} M/u \end{bmatrix} \mathbf{snd}(N) = \mathbf{snd}([M/u]N) \\ \begin{bmatrix} M/u \end{bmatrix} \mathbf{\lambda}v: P.N = \lambda v: P.[M/u]N \qquad (v \neq M) \\ \begin{bmatrix} M/u \end{bmatrix} \lambda v: P.N = \lambda v: P.[M/u]N \qquad (v \neq M) \\ \begin{bmatrix} M/u \end{bmatrix} \mathbf{\lambda}v: P.N = \mathbf{\lambda}v: P.[M/u]N \qquad (v \neq M) \\ \begin{bmatrix} M/u \end{bmatrix} \mathbf{abort}(N) = \mathbf{abort}([M/u]N) \\ \begin{bmatrix} M/u \end{bmatrix} \mathbf{abort}(N) = \mathbf{abort}([M/u]N) \\ \begin{bmatrix} M/u \end{bmatrix} \mathbf{inl}(N) = \mathbf{inl}([M/u]N) \\ \begin{bmatrix} M/u \end{bmatrix} \mathbf{inl}(N) = \mathbf{inl}([M/u]N) \\ \begin{bmatrix} M/u \end{bmatrix} \mathbf{inl}(N) = \mathbf{inl}([M/u]N) \\ \begin{bmatrix} M/u \end{bmatrix} \mathbf{inn}(N) = \mathbf{inn}([M/u]N) \\ \begin{bmatrix} M/u \end{bmatrix} \mathbf{inn}(N) = \mathbf{inn}([M/u]N) \\ \end{bmatrix}$$

case [M/u]N of  $\operatorname{inl}(u_1) \Rightarrow [M/u]N_1 \mid \operatorname{inr}(u_2) \Rightarrow [M/u]N_2$  $(u_1 \ \# \operatorname{FV}(M), u_2 \ \# \operatorname{FV}(M))$ 

The conditions on substitution into a  $\lambda$  or **case** expression mean that the substitution [M/u]N need not be defined! For example, the attempted substitution  $[\langle u, u \rangle / v] \lambda u: P. \langle u, v \rangle$  is undefined, because the bound variable, u, occurs free in  $\langle u, u \rangle$ . However, if we first rename the bound variable of the  $\lambda$ , then substitution is defined:

$$[\langle u, u \rangle / v] \lambda u' : P : \langle u', v \rangle = \lambda u' : P : \langle u', \langle u, u \rangle \rangle.$$

Similarly, the attempted substitution  $[M/u]\lambda u:P.u$  is undefined, because the bound variable name is the same as the target of the substitution. But once again this is not a problem, because by renaming the bound variable to, say, v, where  $v \neq u$ , substitution is once again defined.

The undefinedness of substitution can always be avoided by renaming bound variables so as to ensure that the restrictions on substitution are met.

**Theorem 0.1** 1. For any M, N, and u, there exists N' and N'' such that  $N =_{\alpha} N'$  and [M/u]N' = N''.

2. If  $N =_{\alpha} N'$  and  $N =_{\alpha} N''$  and [M/u]N' and [M/u]N'' both exist, then  $[M/u]N' =_{\alpha} [M/u]N''$ .

Thus we say that substitution is well-defined up to  $\alpha$ -equivalence.

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## **Bound Variable Convention**

Since bound variable names may be chosen arbitrarily, it is technically convenient to ignore the choice by systematically "modding out" by  $\alpha$ -equivalence. This means that we *always* work with  $\alpha$ -equivalence classes of terms, and implicitly choose representatives of each equivalence class so that all relevant substitutions are well-defined. This frees us from having to think about the fundamentally irrelevant choice of bound variable names when manipulating terms.